Interconnection Networks: Topology and Routing

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Topology Overview

- Definition: determines arrangement of channels and nodes in network
- Analogous to road map
- Often first step in network design
- Routing and flow control build on properties of topology

Abstract Metrics

- Use metrics to evaluate performance and cost of topology
- Also influenced by routing/flow control
 - At this stage
 - Assume ideal routing (perfect load balancing)
 - Assume ideal flow control (no idle cycles on any channel)
- Switch Degree: number of links at a node
 - Proxy for estimating cost
 - Higher degree requires more links and port counts at each router

Latency

- Time for packet to traverse network
 - Start: head arrives at input port
 - End: tail departs output port
- Latency = Head latency + serialization latency
 - Serialization latency: time for packet with Length L to cross channel with bandwidth b (L/b)
- Hop Count: the number of links traversed between source and destination
 - Proxy for network latency
 - Per hop latency with zero load

Impact of Topology on Latency

- Impacts average minimum hop count
- Impact average distance between routers
- Bandwidth

Throughput

- Data rate (bits/sec) that the network accepts per input port
- Max throughput occurs when one channel saturates
 - Network cannot accept any more traffic
- Channel Load
 - Amount of traffic through channel c if each input node injects 1 packet in the network

Maximum channel load

- Channel with largest fraction of traffic
- Max throughput for network occurs when channel saturates
 - Bottleneck channel

Bisection Bandwidth

- Cuts partition all the nodes into two disjoint sets
 - Bandwidth of a cut
- Bisection
 - A cut which divides all nodes into nearly half
 - Channel bisection → min. channel count over all bisections
 - Bisection bandwidth → min. bandwidth over all bisections
- · With uniform traffic
 - − ½ of traffic cross bisection

- 3 sends 1/16 of its traffic to 7 (2 possible shortest paths)
- 2 sends 1/8 of its traffic to 4,5
- Etc
- Channel load = 1

Path Diversity

- Multiple minimum length paths between source and destination pair
- Fault tolerance
- Better load balancing in network
- Routing algorithm should be able to exploit path diversity
- We'll see shortly
 - Butterfly has no path diversity
 - Torus can exploit path diversity

Path Diversity (2)

- Edge disjoint paths: no links in common
- Node disjoint paths: no nodes in common except source and destination
- If j = minimum number of edge/node disjoint paths between any source-destination pair
 - Network can tolerate j link/node failures

Symmetry

- Vertex symmetric:
 - An automorphism exists that maps any node a onto another node b
 - Topology same from point of view of all nodes
- Edge symmetric:
 - An automorphism exists that maps any channel a onto another channel b

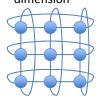
Direct & Indirect Networks

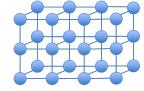
- Direct: Every switch also network end point
- Indirect: Not all switches are end points
 - Ex: Butterfly

- Ex: Torus

Torus (1)

- K-ary n-cube: kⁿ network nodes
- n-dimensional grid with k nodes in each dimension





3-ary 2-outboth

2,3,4-ary 3-mesh

Torus (2)

- Topologies in Torus Family
 - Ring k-ary 1-cube
 - Hypercubes 2-ary n-cube
- Edge Symmetric
 - Good for load balancing
 - Removing wrap-around links for mesh loses edge
 - More traffic concentrated on center channels
- Good path diversity
- Exploit locality for near-neighbor traffic

Torus (3)

$$H_{\min} = \begin{cases} \frac{nk}{4} & k \text{ even} \\ n\left(\frac{k}{4} - \frac{1}{4k}\right) & k \text{ odd} \end{cases}$$

- Hop Count:
- Degree = 2n, 2 channels per dimension

Channel Load for Torus

- Even number of k-ary (n-1)-cubes in outer dimension
- Dividing these k-ary (n-1)-cubes gives a 2 sets of kn-1 bidirectional channels or 4kn-1
- ½ Traffic from each node cross bisection

channel load =
$$\frac{N}{2} \times \frac{k}{4N} = \frac{k}{8}$$

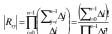
• Mesh has ½ the bisection bandwidth of torus

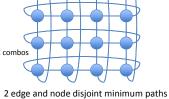
Torus Path Diversity



 $\Delta x = 2, \Delta y = 2$





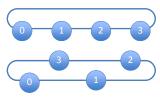


n dimensions with Δi hops in i dimension

*assume single direction for x and y

Implementation

- Folding
 - Equalize path lengths
 - Reduces max link length
 - Increases length of other links



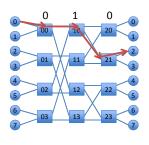
Concentration

- Don't need 1:1 ratio of network nodes and cores/memory
- Ex: 4 cores concentrated to 1 router



Butterfly

- K-ary n-fly: kⁿ network nodes
- Example: 2-ary 3-fly
- Routing from 000 to 010
 - Dest address used to directly route packet
 - Bit n used to select output port at stage n



Butterfly (2)

 $|R_{xy}| = 1$

- No path diversity
 - -,
- Hop Count
 - $-\log_k n + 1$
 - Does not exploit locality
 - Hop count same regardless of location
- Switch Degree = 2k
- Channel Load → uniform traffic

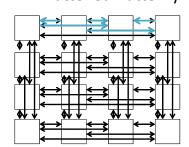
$$\frac{NH_{\min}}{C} = \frac{k^{n}(n+1)}{k^{n}(n+1)} = 1$$

- Increases for adversarial traffic

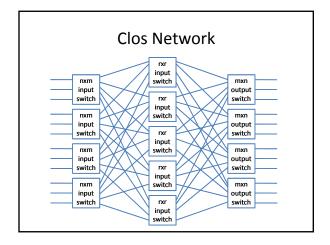
Flattened Butterfly

- Proposed by Kim et al (ISCA 2007)
 - Adapted for on-chip (MICRO 2007)
- Advantages
 - Max distance between nodes = 2 hops
 - Lower latency and improved throughput compared to mesh
- Disadvantages
 - Requires $\stackrel{-}{\mbox{\sc higher}}$ port count on switches (than mesh, torus)
 - Long global wires
 - Need non-minimal routing to balance load

Flattened Butterfly

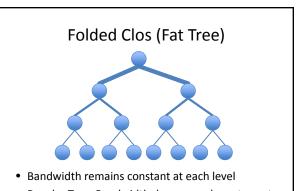


• Path diversity through non-minimal routes

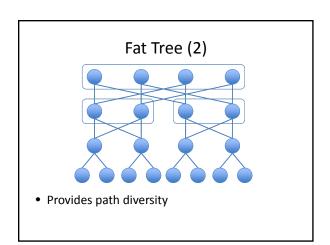


Clos Network

- 3-stage indirect network
- Characterized by triple (m, n, r)
 - M: # of middle stage switches
 - N: # of input/output ports on input/output switches
 - R: # of input/output switching
- Hop Count = 4



• Regular Tree: Bandwidth decreases closer to root



Common On-Chip Topologies

- Torus family: mesh, concentrated mesh, ring
 - Extending to 3D stacked architectures
 - Favored for low port count switches
- Butterfly family: Flattened butterfly

Topology Summary

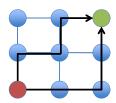
- First network design decision
- Critical impact on network latency and throughput
 - Hop count provides first order approximation of message latency
 - Bottleneck channels determine saturation throughput

Routing Overview

- Discussion of topologies assumed ideal routing
- Practically though routing algorithms are not ideal
- Discuss various classes of routing algorithms
 - Deterministic, Oblivious, Adaptive
- Various implementation issues
 - Deadlock

Routing Basics

- · Once topology is fixed
- Routing algorithm determines path(s) from source to destination



Routing Algorithm Attributes

- Number of destinations
 - Unicast, Multicast, Broadcast?
- Adaptivity
 - Oblivious or Adaptive? Local or Global knowledge?
- Implementation
 - Source or node routing?
 - Table or circuit?

Oblivious

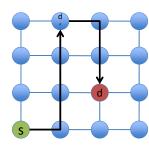
- Routing decisions are made without regard to network state
 - Keeps algorithms simple
 - Unable to adapt
- Deterministic algorithms are a subset of oblivious

Deterministic

- All messages from Src to Dest will traverse the same path
- Common example: Dimension Order Routing (DOR)
 - Message traverses network dimension by dimension
 - Aka XY routing
- Cons:
 - Eliminates any path diversity provided by topology
 - Poor load balancing
- Pros:
 - Simple and inexpensive to implement
 - Deadlock free

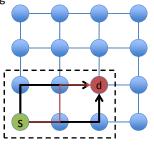
Valiant's Routing Algorithm

- To route from s to d, randomly choose intermediate node d'
 - Route from s to d' and from d' to d.
- Randomizes any traffic pattern
 - All patterns appear to be uniform random
 - Balances network load
- Non-minimal



Minimal Oblivious

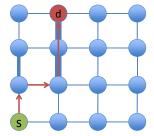
- Valiant's: Load balancing comes at expense of significant hop count increase
 - Destroys locality
- Minimal Oblivious: achieve some load balancing, but use shortest paths
 - d' must lie within minimum quadrant
 - 6 options for d'
 - Only 3 different paths



Adaptive

- Uses network state to make routing decisions
 - Buffer occupancies often used
 - Couple with flow control mechanism
- · Local information readily available
- Global information more costly to obtain
- Network state can change rapidly
- Use of local information can lead to non-optimal choices
- Can be minimal or non-minimal

Minimal Adaptive Routing

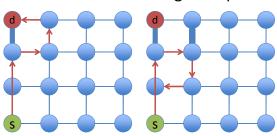


• Local info can result in sub-optimal choices

Non-minimal adaptive

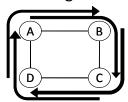
- Fully adaptive
- Not restricted to take shortest path
 - Example: FBfly
- Misrouting: directing packet along nonproductive channel
 - Priority given to productive output
 - Some algorithms forbid U-turns
- Livelock potential: traversing network without ever reaching destination
 - Mechanism to guarantee forward progress
 - Limit number of misroutings

Non-minimal routing example

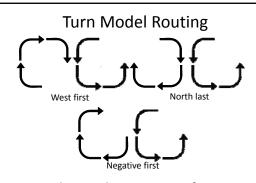


- Longer path with potentially lower latency
- Livelock: continue routing in

Routing Deadlock

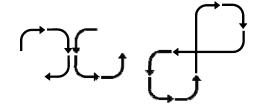


- Without routing restrictions, a resource cycle can occur
 - Leads to deadlock



- Some adaptivity by removing 2 of 8 turns
 - Remains deadlock free (like DOR)

Turn Model Routing Deadlock



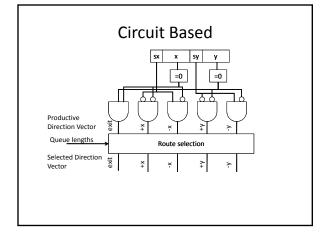
- Not a valid turn elimination
 - Resource cycle results

Routing Implementation

- Source tables
 - Entire route specified at source
 - Avoids per-hop routing latency
 - Unable to adapt to network conditions
 - Can specify multiple routes per destination
- Node tables
 - Store only next routes at each node
 - Smaller tables than source routing
 - Adds per-hop routing latency
 - Can adapt to network conditions
 - Specify multiple possible outputs per destination

Implementation

- · Combinational circuits can be used
 - Simple (e.g. DOR): low router overhead
 - Specific to one topology and one routing algorithm
 - Limits fault tolerance
- Tables can be updated to reflect new configuration, network faults, etc



Routing Summary

- Latency paramount concern
 - Minimal routing most common for NoC
 - Non-minimal can avoid congestion and deliver low latency
- To date: NoC research favors DOR for simplicity and deadlock freedom
 - On-chip networks often lightly loaded
- Only covered unicast routing
 - Recent work on extending on-chip routing to support multicast

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